

AVACS Autumn School @ Oldenburg

# Precision of BlackBox Verification Techniques: Hardness and Technology

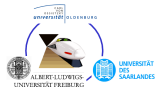


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October 1st, 2015

Chair of  
Computer  
Architecture

University of Freiburg



# Acknowledgements

- *Bernd Becker*
- *Karina Gitina*
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- *Sven Reimer*
- *Christoph Scholl*
- *Ralf Wimmer*
- ...



# Why Verification?

## Safety & Security

- Human life
- Money risk
- A project's development cost

## Our Target

- Incomplete designs
- Discrete systems

# AVACS TP-S1: Systems of Systems

- **Automatic verification methods**
  - Distributed systems
  - Statically connected components
- **Compositional approach** ←
- Miniaturization
  - Reuse of components
- **Embedded Systems**  
**System on Chip** ←

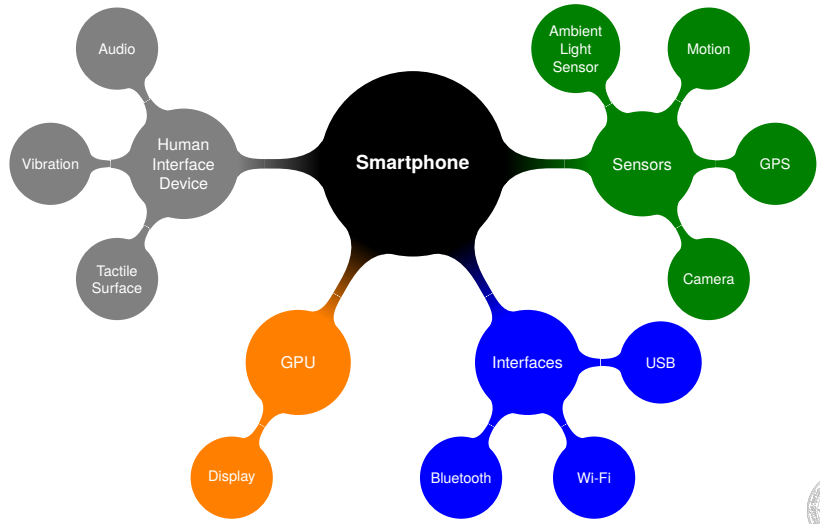


# AVACS TP-S1: Systems of Systems

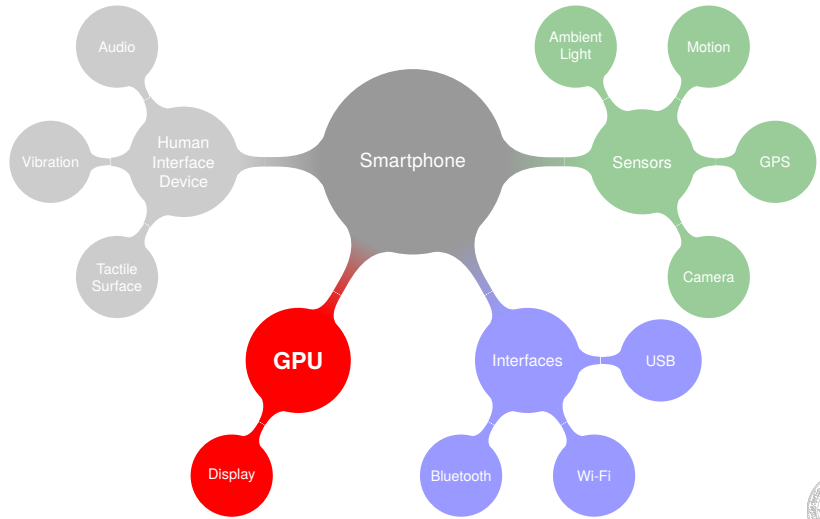
- **Automatic verification methods**
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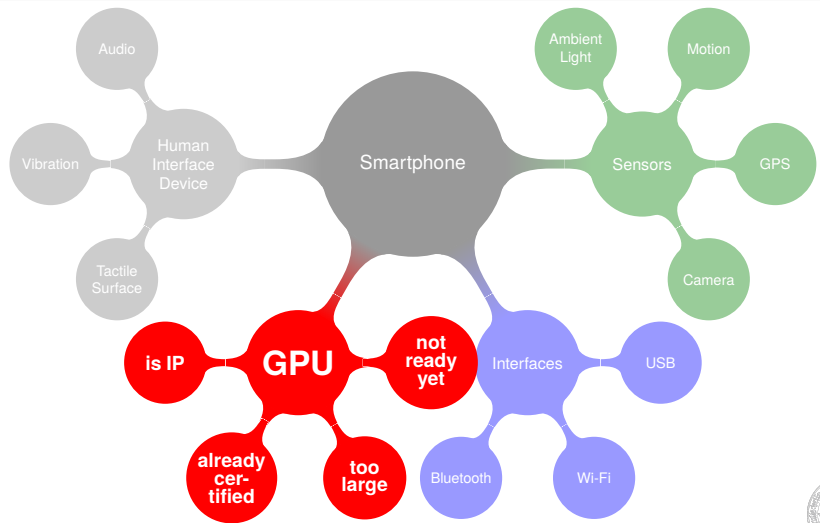
# A Very Simple Example



# A Very Simple Example



# A Very Simple Example





# Our Challenge

## Verification of Incomplete Designs

### Combinational Circuits

Is there any input vector that makes the given system produce a different output from the specification?

**Validation**

### Sequential Circuits

Is there a sequence of inputs so that eventually the system output does not fulfill the specification?

**Property checking**

**What happens if our design is incomplete?**



# Our Challenge

## Verification of Incomplete Designs

### Combinational Circuits

Is there any input vector that makes the given system produce a different output from the specification?

Validation →

Equivalence Checking

### Sequential Circuits

Is there a sequence of inputs so that eventually the system output does not fulfill the specification?

Property checking →

Model Checking

**What happens if our design is incomplete?**



# Our Challenge

## Verification of Incomplete Designs

### Combinational Circuits

Is there a Blackbox implementation that makes the implementation fulfill the specification?

Realizability →  
Equivalence Checking

### Sequential Circuits

Is there a sequence of inputs so that eventually the system output does not fulfill the specification?

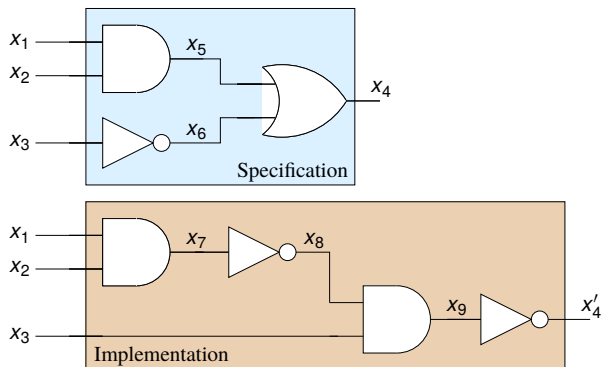
Property checking →  
Bounded Model Checking

**What happens if our design is incomplete?**



# Formal Verification for Combinational Circuits

Let the specification and the implementation of a combinational circuit be defined as follows



Question: are specification and implementation equivalent?

# Circuit Equivalence Checking

- Formally prove whether the two circuits differ
- Construction of a BDD via symbolic simulation  
High memory requirements

Optimizations possible (e.g. computation of equivalent sub-circuits via simulation)

–• Solving a satisfiability problem

## Focus

SAT based equivalence checking



# Propositional Logic: Syntax

## Definition

Let  $x_1, \dots, x_n$  be a set of Boolean variables. A **propositional logic formula** is defined inductively as:

- A variable  $x_i$  is a formula.
- For every formulas  $F_1$  and  $F_2$ 
  - the conjunction  $(F_1 \wedge F_2)$  and
  - the disjunction  $(F_1 \vee F_2)$  are also formulas.
- For every formula  $F$ , its negation  $(\neg F)$  is a formula.
- A formula  $F$  is in conjunctive normal form (CNF) iff
  - $F$  is the conjunction of  $n \geq 0$  **clauses**  $(C_1 \wedge C_2 \wedge \dots \wedge C_n)$
  - which are the disjunction of  $m \geq 0$  **literals**  $(l_1 \vee l_2 \vee \dots \vee l_m)$
  - and a literal is a variable  $x$  or its negation  $\neg x$

Transformation into CNF requires linear time.



# Propositional Logic: SAT Problem

## Definition

- A propositional logic formula  $F$  is **satisfiable** iff there exists an assignment  $\mathcal{A}(F) = 1$ .
- It is common to say that one of these kinds of assignments, also called **Model**, satisfies the formula  $F$ , and is represented with  $\mathcal{A} \models F$ .
- On the other hand, if there exist no assignment  $\mathcal{A}$  such that  $\mathcal{A}(F) = 1$ , then  $F$  is unsatisfiable. For every such assignment  $\mathcal{A}$  then  $\mathcal{A} \not\models F$ .



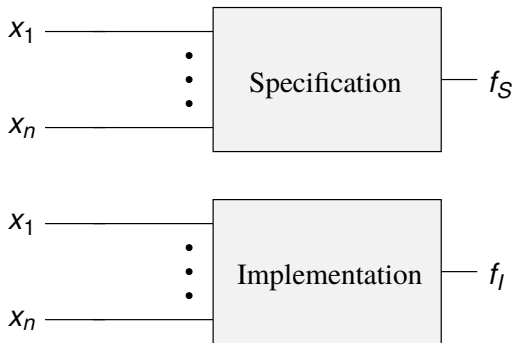
# SAT for the Verification of Combinational Circuits

- Given
  - Specification and implementation of a combinational circuit
- Question
  - Are the specification and the implementation equivalent?
- Approach for SAT-based equivalence checking
  - Generate a so-called **miter**-circuit joining specification and implementation
  - Build a Boolean formula from the miter representation
  - Solve the formula with a SAT algorithm
- The specification and the implementation of a combinatorial circuit are equivalent iff the Boolean formula generated from the miter is unsatisfiable



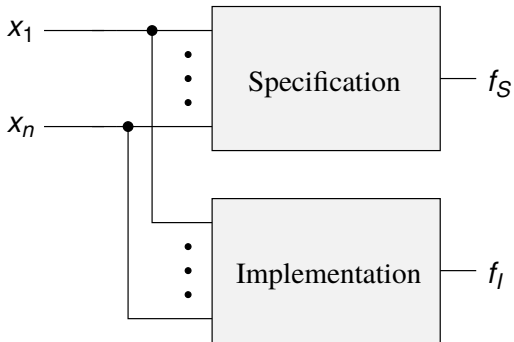


# Construction of the Miter Circuit



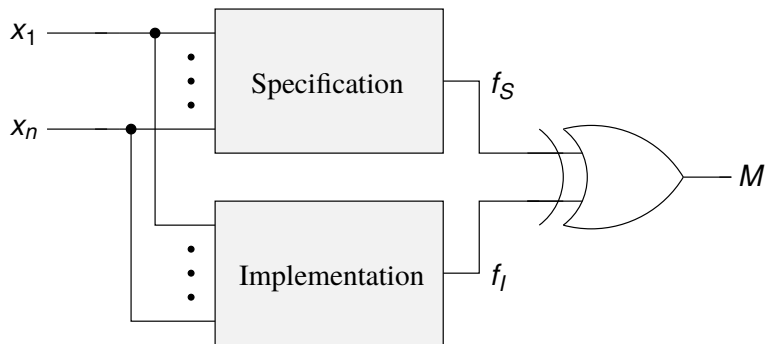
⇒ Connect corresponding inputs

# Construction of the Miter Circuit



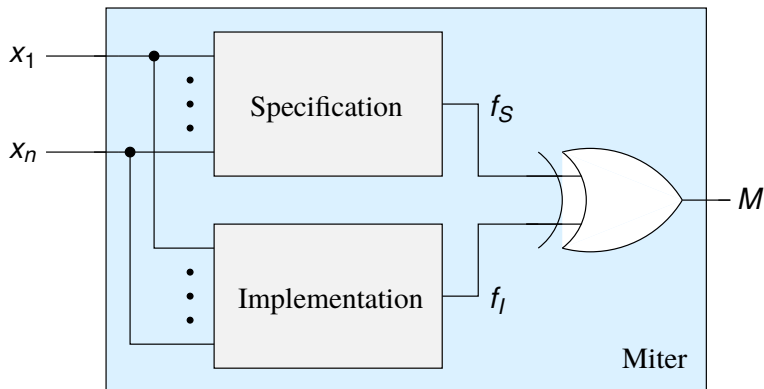
⇒ Link corresponding outputs by EXOR gates

# Construction of the Miter Circuit



⇒ Miter circuit

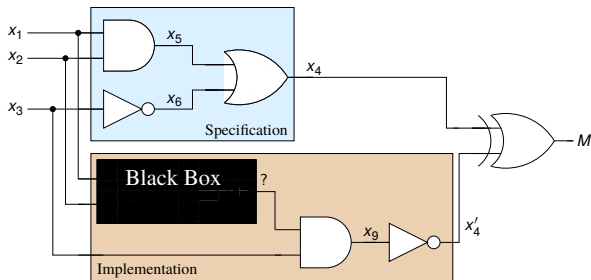
# Construction of the Miter Circuit



$\Rightarrow M = 1 \Leftrightarrow$  Specification & Implementation not equivalent

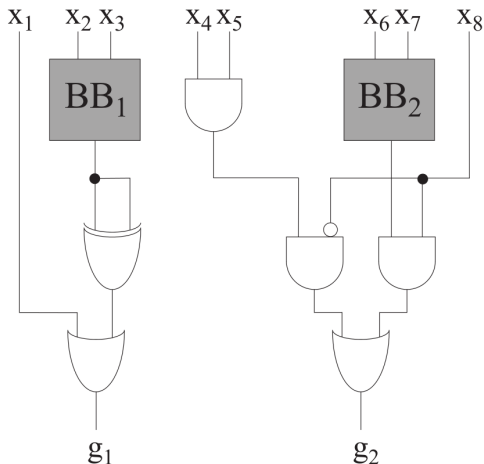
# Partial Equivalence Checking [Scholl, Becker 2001]

- Part of the design replaced by a Blackbox
- Output modeled as an **Unknown** value
- 01X-Logic 3-valued signals [Jain 2000]



**Realizability** problem: If unrealizability is returned, it **may** depend on a too coarse approximation

## Coarse Approximation: Example



Constant 0 XOR gate output not detectable using 01X logic.

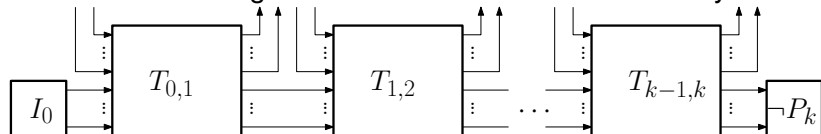
# Formal Verification for Sequential Systems

- Functional equivalence of two sequential circuits can be proved
- A specification which cannot be expressed as a sequential circuit or a deterministic finite state automaton cannot be proved
  - safety properties
  - liveness properties
- The resulting problem must be decidable
  - temporal structure
  - temporal logics  $\rightarrow$  e.g. **CTL**
  - proof system
- **We restrict properties to invariants**



# Bounded Model Checking

Sequential designs: behaviour depending on inputs and time  
 → Model checking: conversion into a combinational system



Iteratively unfold the system  $k$  times. The SAT-based BMC formula

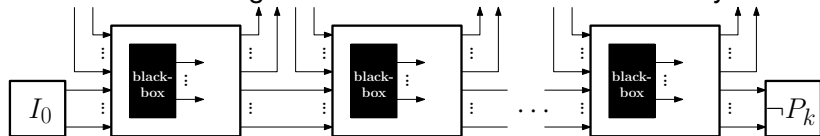
$$I_0 \wedge T_{0,1} \wedge \dots \wedge T_{k-1,k} \wedge \neg P_k$$

evaluates to  $\top$  iff there exists a counterexample of length  $k$  that violates the safety property.



# Bounded Model Checking for Incomplete Designs

Sequential designs: behaviour depending on inputs and time  
 → Model checking: conversion into a combinational system



Iteratively unfold the system  $k$  times. The SAT-based BMC formula

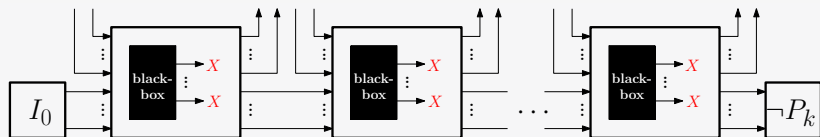
$$I_0 \wedge T_{0,1} \wedge \dots \wedge T_{k-1,k} \wedge \neg P_k$$

evaluates to  $\top$  iff there exists a counterexample of length  $k$  that violates the safety property **regardless of the implementation of the blackbox.**



# BB-BMC: Limits [Herbstritt et al. 2006]

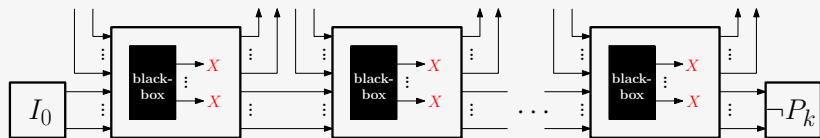
**01X-modeling:** apply the value  $X$  to all blackbox outputs



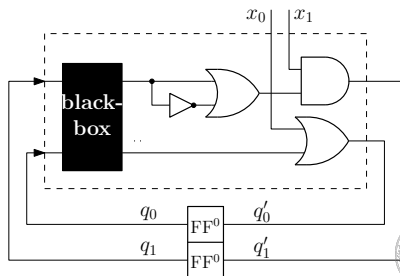
- 3-valued encoding [Jain 2000]
  - transformation to CNF [Tseitin 1968]
- ⇒ SAT problem
- $X$  may “propagate” to  $\neg P_k$

# BB-BMC: Limits [Herbstritt et al. 2006]

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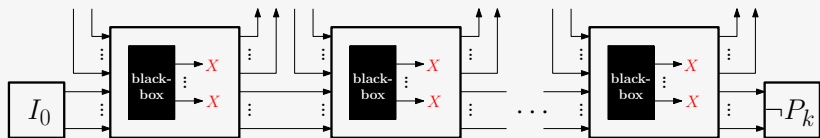


- $\neg P_k: (q_0 \wedge q_1)$
- $q_1$  evaluates to 0 or  $X$
- counterexample not found

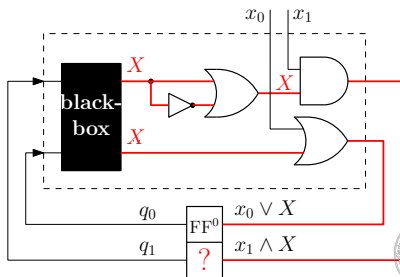


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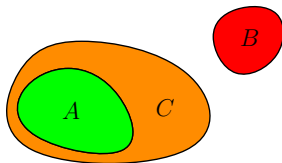
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## BMC and Craig Interpolation [McMillan 2003]

$$\underbrace{I_0 \wedge T_{0,1}}_A \wedge \underbrace{T_{1,2} \wedge \dots \wedge T_{k-1,k} \wedge \neg P_k}_B$$

- Craig interpolant  $C$  of  $A$  and  $B$ 
  - Over-approximation of the reachable states
  - Implied by  $A$
  - Contains only AB-common variables (here: latches)
  - Unsatisfiable in conjunction with  $B$

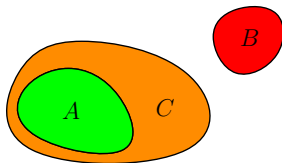


- If a fixpoint of the reachable states reached  
 $\Rightarrow$  unsatisfiable for every unfolding depth  $\Rightarrow$  01X-hard

## BMC and Craig Interpolation [McMillan 2003]

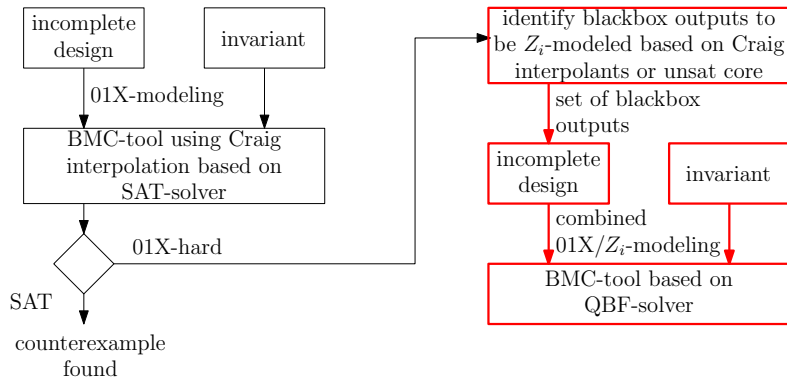
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# BB-BMC Workflow [Miller et al, 2010]



# Heuristics for Identifying Blackbox Outputs

- **Exploiting Craig interpolant**

- Analyze last computed Craig interpolant  $C$
- Perform cone-of-influence analysis on all latches in  $C$
- Model all blackbox outputs influencing these latches using  $Z_i$

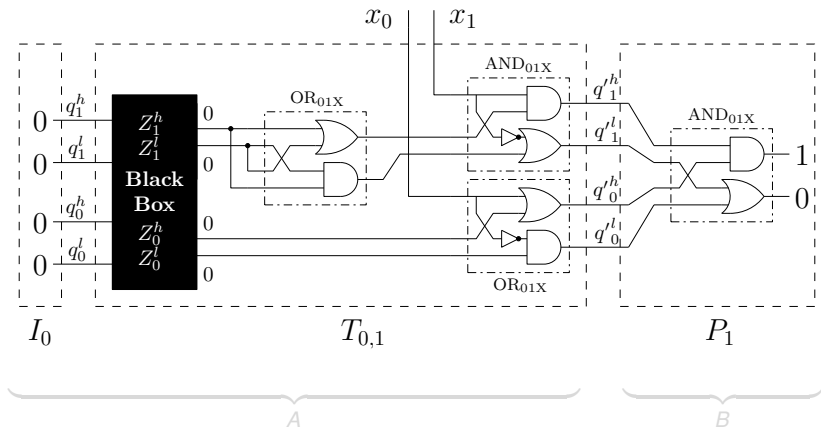
- **Exploiting unsatisfiable core**

- Determine unsatisfiable core at unfolding depth where the fixed-point was found
- Blackbox outputs included in this unsatisfiable core directly influence the unsatisfiability of the problem
- Model these blackbox outputs using  $Z_i$



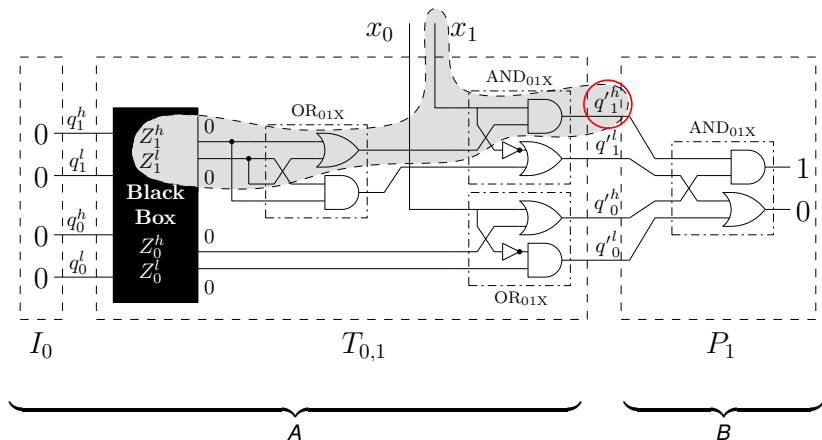


## Exploiting Craig Interpolants



- Derived Craig interpolant  $C = \neg(q_1^h)$
- $Z_1$  has influence on latch in  $C$ .
- Model  $Z_1$  using  $Z_i$  and  $Z_0$  using 01X.

## Exploiting Craig Interpolants



- Derived Craig interpolant  $C = \neg(q_1^h)$
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- Model  $Z_1$  using  $Z_i$  and  $Z_0$  using 01X.

# Logic of Quantified Boolean Formulas

## Syntax of QBF

Let  $x_1, \dots, x_n$  be a set of variables. A **QBF logic** is defined through the following inductive process:

- Every propositional logic formula and every variable  $x_i$  are QBF formulas.
- The constants **true** ( $1, \top$ ) and **false** ( $0, \perp$ ) are QBF formulas.
- For every QBF formula  $F$ ,  $\exists xF$  and  $\forall xF$  are QBF formulas.
- For every formula  $F_1$  and  $F_2$ ,  $\neg F_1$ ,  $(F_1 \wedge F_2)$ , and  $(F_1 \vee F_2)$  are QBF formulas.



# Logic of Quantified Boolean Formulas

## Definition (Semantics of QBF Logic)

An **assignment**  $\mathcal{A}_x : \{x_1, \dots, x_n\} \rightarrow \{0, 1\}$  is a mapping that assigns either the value 0 or 1 to a variable of the formula and satisfies the following conditions:

- For each variable  $x_i$  contained in  $F$ :
  - $\mathcal{A}(x_i) = \mathcal{A}_x(x_i)$ .
- For each constant formula 0 or 1:
  - $\mathcal{A}(0) = 0, \mathcal{A}(1) = 1$
- For each subformula  $F_1$  and  $F_2$  of  $F$ :
  - $\mathcal{A}(F_1 \wedge F_2) = 1 \Leftrightarrow \mathcal{A}(F_1) = 1$  and  $\mathcal{A}(F_2) = 1$ .
  - $\mathcal{A}(F_1 \vee F_2) = 1 \Leftrightarrow \mathcal{A}(F_1) = 1$  or  $\mathcal{A}(F_2) = 1$ .
- For each subformula  $F'$  of  $F$ :
  - $\mathcal{A}(\neg F') = 1 \Leftrightarrow \mathcal{A}(F') = 0$ .
  - $\mathcal{A}(\exists x_i F') = 1 \Leftrightarrow \mathcal{A}_x(F')$  or  $\mathcal{A}_{\neg x}(F') = 1$ .
  - $\mathcal{A}(\forall x_i F') = 1 \Leftrightarrow \mathcal{A}_x(F') = \mathcal{A}_{\neg x}(F') = 1$ .



# Logic of Quantified Boolean Formulas

The prefix defines the dependencies among the variables in a linear way. Given a formula  $F$  whose prefix is  $Q_1x_1Q_2x_2\dots Q_nx_n$

## Definition (Quantifier alternations)

We define quantifier alternation as the number of switchings between  $\forall$  and  $\exists$  quantifiers reading the prefix from left to right.

## Definition (Level of a variable)

The level of a variable  $x_i$  is 1 plus the number of alternations that precede it. It is common to use the terms **outermost** quantifier level to indicate the level 0, and **innermost** quantifier level to indicate that “beside” the matrix.



# Logic of Quantified Boolean Formulas

## Definition (Prenex Conjunctive Normal Form, PCNF)

A QBF formula  $F$  is in **prenex conjunctive normal form (PCNF)** iff it is a **prefix** and a **matrix**, where the matrix is a conjunction of clauses:

$$F = Q_1 X_1 Q_2 X_2 \dots Q_n X_n \bigwedge_{j=1}^m C_j \quad \text{with } C_1, \dots, C_m \text{ Clauses}$$

- Example:  $\exists x_1 \exists x_2 \forall x_3 \exists x_4 (x_1 \vee \neg x_2 \vee x_3) \wedge (x_2 \vee x_4)$
- An assignment  $\mathcal{A}$  satisfies a CNF formula  $F$  iff every clause in  $F$  is satisfied. **Wrong!** We have to follow the semantics imposed by the prefix.

# $Z_i$ -Encoding: PEC

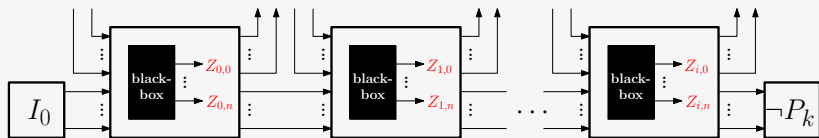
- Blackbox outputs act as additional primary inputs
- Encoded as universal variables
- “No matter what the Blackbox does” the rest must hold
- Exact if the system includes 1 Blackbox
- Additional constraints to make the Blackbox’s output consistent (combinational)
- Compromise between precision and speed

$$\exists \bar{X} \forall Z_i, \exists \bar{Y}, M. (\phi(\bar{X}, Z_i, \bar{Y}, M) \wedge (M \equiv 1))_{CNF} \quad ?$$



# $Z_j$ -Encoding: BB-BMC

**$Z_j$ -modeling:** use one  $\forall$ -variable for each blackbox output

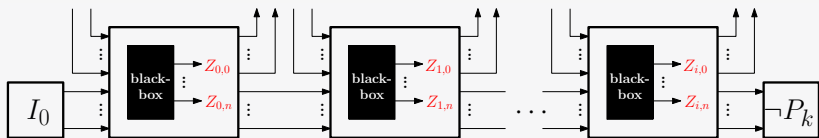


- Blackbox outputs are **universally quantified**
  - Tseitin transformation
  - Prefix generation (see next slide)
- ⇒ QBF problem
- more precise

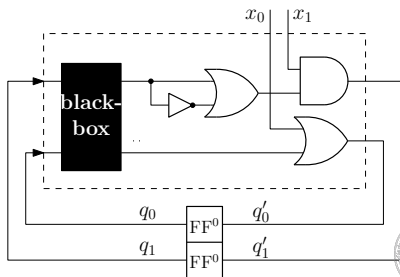


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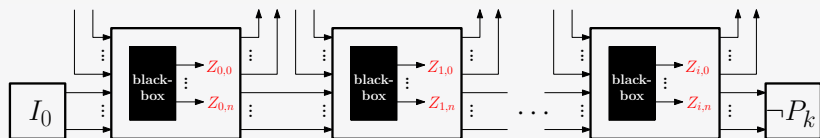


- $\neg P_k: (q_0 \wedge q_1)$
- $\exists x_0 x_1 \forall z_0 z_1 \exists \vec{H}$  CNF
- satisfied for  $x_0 = 1, x_1 = 1$

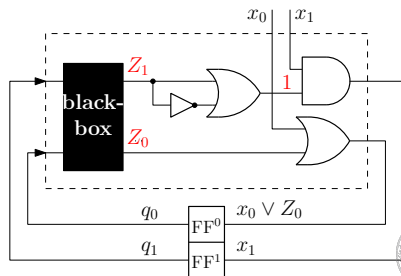


# $Z_i$ -Encoding: BB-BMC

**$Z_i$ -modeling:** use one  $\forall$ -variable for each blackbox output



- $\neg P_k: (q_0 \wedge q_1)$
- $\exists x_0 x_1 \forall \mathbf{Z}_0 \mathbf{Z}_1 \exists \vec{H} \text{ CNF}$
- satisfied for  $x_0 = 1, x_1 = 1$



## $Z_j$ -Encoding: BB-BMC

**Non-uniform** quantifier prefix ( $pref_1$ ):

$$\underbrace{\exists x_{0,0}, \dots, x_{n,0} \quad \forall Z_{0,0}, \dots, Z_{m,0} \quad \exists H_0 \dots}_{\text{depth } 0} \quad \underbrace{\exists x_{0,k}, \dots, x_{n,k} \quad \forall Z_{0,k}, \dots, Z_{m,k} \quad \exists H_k}_{\text{depth } k}$$

- inputs can “react” to the values of the blackbox outputs
- $2 \cdot (k + 1)$  quantifier alternations

**Uniform** quantifier prefix ( $pref_2$ ):

$$\underbrace{\exists x_{0,0}, \dots, x_{n,k}}_{\substack{\text{primary inputs} \\ \text{depth } 0 \dots k}} \quad \underbrace{\forall Z_{0,0}, \dots, Z_{m,k}}_{\substack{\text{blackbox outputs} \\ \text{depth } 0 \dots k}} \quad \underbrace{\exists H_0, \dots, H_k}_{\substack{\text{Tseitin} \\ \text{depth } 0 \dots k}}$$

- exactly one input sequence
- 2 quantifier alternations
- $pref_2 \implies pref_1$



# Incremental SAT [Een 2003]

- Incremental SAT Problem: within a loop, the input formula is augmented by new sub-expressions
- Advantages: reuse of conflict clauses and decision heuristic scores
- Assumptions to unconstrain running formula

## Use of Assumptions

$\varphi = (x \vee y) \wedge (\neg x \vee y \vee z)$  non incremental

$\varphi_{0/-w} = (x \vee y) \wedge (\neg x \vee y \vee z \vee w)$  incr. step 0

$\varphi_{1/w} = (x \vee y) \wedge (\neg x \vee y \vee z \vee w) \wedge (\dots)$  incr. step 1



# Incremental QBF Solving Problem

- step 0:  $\Phi_0 = Q_1 X_1^0 \dots Q_n X_n^0 \phi_0$
- ...
- step  $i$ :  $\Phi_i = Q_1 X_1^0 \dots X_1^i \dots Q_n X_n^0 \dots X_n^i \phi_{i-1} \setminus \phi_i^- \wedge \phi_i^+$



# Incremental QBF Solving Problem

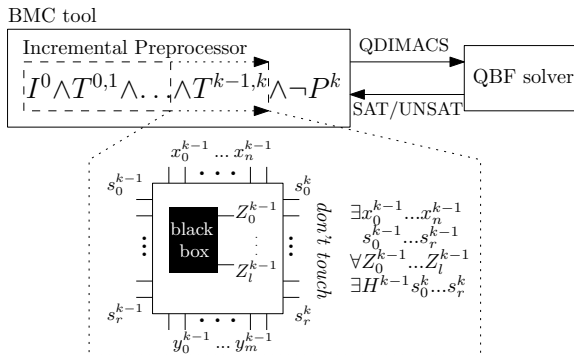
- step 0:  $\Phi_0 = Q_1 X_1^0 \dots Q_n X_n^0 \phi_0$
- ...
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## Howto

- Assumption-based solving
- Add new variables to existing quantifier blocks
- Add new quantifier blocks
- Add and delete clauses
- Avoid memory reallocation and fragmentation
- Keep learned clauses, learned solution cubes only in special cases



## Incremental QBF Preprocessing [Miller et al., 2012]



- Idea: keep a compact (preprocessed) representation of current unfolding  $I_0 \wedge T_{0,1} \wedge \dots \wedge T_{k-1,k}$  in the incremental preprocessor.
- Preserve interface using *dont-touch/frozen* variables.

# Standard/Incremental BMC Procedures

BMC tool		QBF solver
$I_0 \wedge \neg P_0$	→	preprocess → solve
$I_0 \wedge T_{0,1} \wedge \neg P_1$	→	preprocess → solve
$I_0 \wedge T_{0,1} \wedge T_{1,2} \wedge \neg P_2$	→	preprocess → solve
⋮		⋮
$I_0 \wedge T_{0,1} \wedge T_{1,2} \wedge \dots \wedge T_{k-1,k} \wedge \neg P_k$	→	preprocess → solve

## Standard BMC

- For each unfolding, the QBF formula is directly passed to the QBF solver.
- The QBF solver may invoke a preprocessor before solving the formula.
- At every step the whole formula is preprocessed!





# Standard/Incremental BMC Procedures

BMC tool		QBF solver
$I_0 \wedge \neg P_0$	→	preprocess → solve
$I_0 \wedge T_{0,1} \wedge \neg P_1$	→	preprocess → solve
$I_0 \wedge T_{0,1} \wedge T_{1,2} \wedge \neg P_2$	→	preprocess → solve
⋮	⋮	↓ ⋮ ↓
$I_0 \wedge T_{0,1} \wedge T_{1,2} \wedge \dots \wedge T_{k-1,k} \wedge \neg P_k$	→	preprocess → solve

## Incremental Solving

- Reuse learnt information during solving process.
- Preprocessor may eliminate variables and delete/merge/add clauses.
  - Learnt information not valid anymore → deactivate preprocessing
  - At least pre-preprocess the transition relation



# Standard/Incremental BMC Procedures

BMC tool			QBF solver
$I_0 \wedge \neg P_0$	→	preprocess	→ solve
		↓	
$I_0 \wedge T_{0,1} \wedge \neg P_1$	→	preprocess	→ solve
		↓	
$I_0 \wedge T_{0,1} \wedge T_{1,2} \wedge \neg P_2$	→	preprocess	→ solve
		↓	
⋮		⋮	⋮
		↓	
$I_0 \wedge T_{0,1} \wedge T_{1,2} \wedge \dots \wedge T_{k-1,k} \wedge \neg P_k$	→	preprocess	→ solve

## Incremental Preprocessing

- Move preprocessor to the BMC tool.
- Reuse the preprocessed QBF formula for the construction of the next unfolding.

# Standard/Incremental BMC Procedures

## Incremental Reasoning

- Incremental preprocessing can become slow
- Hybrid way: eventually switch from incremental preprocessing to incremental solving

# Standard/Incremental BMC Procedures

## Incremental Reasoning

- Because of the linear prefix a QBF formula can be incrementally extended “to the left”, “to the right”, or keeping the initial quantifier alternations
- Backwards incremental solving more efficient (solution learning)
- Forwards incremental preprocessing is more effective (Tseitin auxiliary variables elimination)
- Matter of heuristics



01X vs  $Z_i$ 

- Uniform faster
- 01X fastest
- Uniform more precise
- Non-uniform most precise
- ...
- The “right solver” can speed up the process
- How to select the right encoding for a specific Blackbox?

## Is $Z_i$ -QBF Precise Enough?

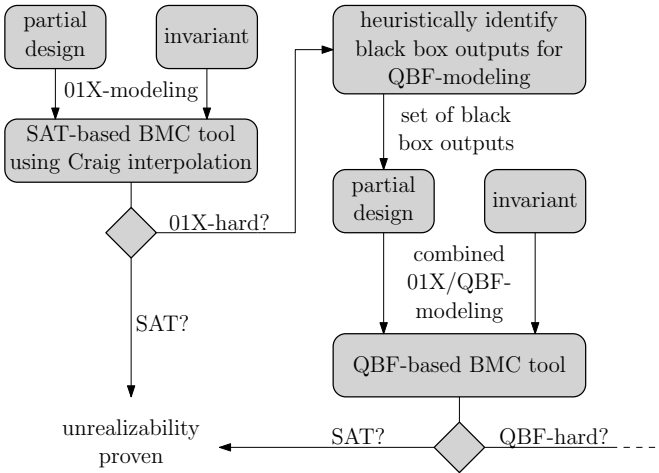
### PEC

A  $Z_i$ -encoded PEC problem is exact iff its underapproximation (BB-outputs depending on all inputs) and its overapproximation (some or all BB-outputs are independent on some primary inputs) return the same result.

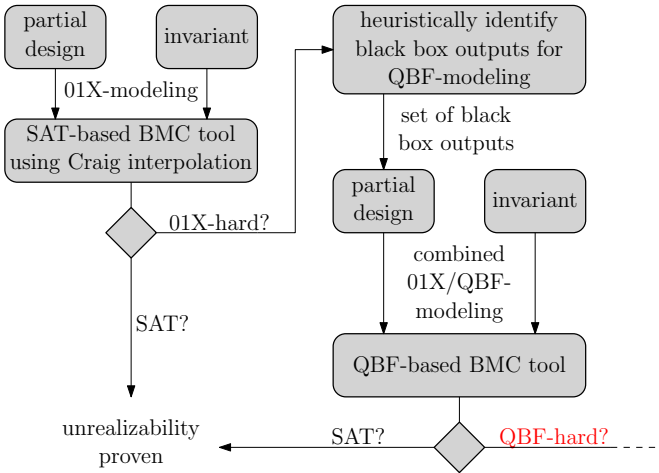
### BB-BMC

Approximate if multiple Blackboxes do not have complete knowledge about the inputs

# BB-BMC Verification Workflow



# BB-BMC Verification Workflow





# BB-BMC: Is $Z_i$ -QBF precise enough?

## QBF-Hardness [Miller et al., 2013]

A partial design is QBF-hard iff the (pure)  $Z_i$ -modeled BMC problem is unsatisfiable for all unfoldings and the property is definitely realizable.

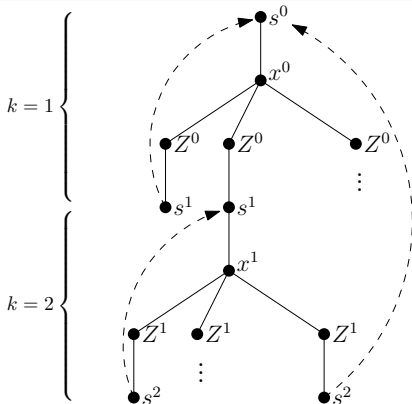
⇒ Prove QBF-hardness using the following iterative procedure...



# Proving QBF-Hardness

Iteratively search for graph with the following properties:

- (1)  $s^0$  fulfills  $P$
- (2) For each  $x^i$  there exists a  $Z^i$  such that  $s^{i+1}$ 
  - is either equivalent to a state which was explored before
  - or it fulfills  $P$  and (2) for next  $i$



- Formulate procedure as QBF problems
- If such graph exists the design is QBF-hard
- Otherwise need “higher” logic

# Dependency Quantified Boolean Formulas

- Generalization of QBF
- Allow arbitrary partially ordered dependencies
- Dependencies of existential variables on universal ones explicitly stated
- Variable order in the prefix irrelevant

## Example

$$\forall x_1 \forall x_2 \exists y_1(x_1) \exists y_2(x_2) : \varphi$$

- $y_1$  depends only on  $x_1$
- $y_2$  depends only on  $x_2$



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# Semantics of QBF and DQBF

**QBF:**

$$\forall x_1 \exists y_1 \forall x_2 \exists y_2 : \varphi$$

is satisfied iff there are functions  $s_{y_1}$  and  $s_{y_2}$  such that replacing  $y_1$  with  $s_{y_1}(x_1)$  and  $y_2$  with  $s_{y_2}(x_1, x_2)$  yields a tautology.



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$\Rightarrow s_{y_1}$  and  $s_{y_2}$  are called **Skolem functions**.



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$\Rightarrow$   $s_{y_1}$  and  $s_{y_2}$  are called **Skolem functions**.

Easy example of cyclic dependency.





# Complexity

- **SAT:**  
Deciding satisfiability of SAT is NP-complete
- **QBF:**  
Deciding satisfiability of QBF is PSPACE-complete
- **DQBF:**  
Deciding satisfiability of DQBF is NEXPTIME-complete



# Preprocessing: necessary

## Inherited from QBF

- Syntactic and semantic unit literal elimination
- Pure literal elimination
- Equivalent literals
- Blocked clauses elimination
- Universal variable expansion  $\Rightarrow$  simplification into QBF
- **Dependency sets can be cyclic!**

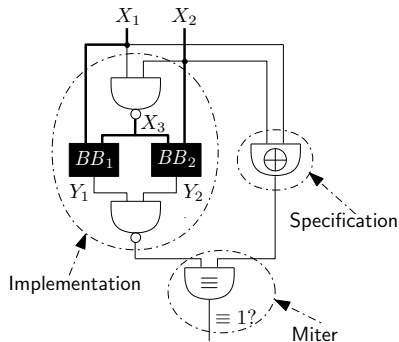
## Newly developed for DQBF [Wimmer et al., 2015]

- More expensive checks are effective
- Variable elimination via D-Q-Resolution more restricted
- Reduction of dependency sets



# PEC via DQBF [Gitina et al. 2013]

Are there implementations of the Blackboxes such that implementation and specification become equivalent?



DQBF formulation:

$$\forall X_1 \forall X_2 \forall X_3 \exists Y_1(X_1, X_3) \exists Y_2(X_2, X_3) : \phi$$

The Blackboxes are in topological order to guarantee that the circuit is combinational

# BB-BMC via DQBF

- We can prove which Blackboxes require to be modeled using DQBF
- How to encode the problem is clear
- Some DQBF solvers are available
- A general and precise BB-BMC tool is definitely demanded
- Robustness and good performance are needed



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- Some DQBF solvers are available
- A general and precise BB-BMC tool is definitely demanded
- Robustness and good performance are needed
- So far: open problem/future work



# Summary

- Formal verification of incomplete discrete systems
- Partial equivalence checking of combinational circuits
- Blackbox-bounded model checking of sequential systems
- SAT: 01X modeling fastest, well studied core algorithms and data structures, suitable to simplest topologies
  - ★ NP-COMPLETE
- QBF:  $Z_i$  modeling stable technology, industrial acceptance required
  - ★ PSPACE-COMPLETE
- DQBF: **explicit dependency** encoding, young and currently under development
  - ★ NEXPTIME-COMPLETE

